

Abstract:

Operations and Flight Calibration of the Swift X-ray Telescope (XRT)

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XRT/UVOT nent boresight, plate

We present the current on-orbit operational plans and calibration plans for the Swift XRT. The XRT is a largely autonomous instrument and requires very little manual commanding for normal operations. A detailed calibration plan is being developed to verify the instrument performance on-orbit, including effective area, point spread function, vignetting, spectroscopic performance, and timing accuracy. Operational plans include regular calibration measurements using on-board sources as well as periodic calibration observations using celestial targets.

> Snapshot Bias |PD |Image |--- PD-TDRSS

messages:

CentroidPosition Messag Postage StampImage Message

Raw Spectrum Message

The Swift XRT has three key science goals:

1) Determine GRB position with 5 arcsecond accuracy and transmit position to the ground within 100 s of the burst.

2) Measure the afterglow lightcurve

3) Obtain X-ray spectroscopy of the afterglow



hottom left); measured PSF (right)

The Point Spread Function (PSF) of the XRT telescope has been measured at the Panter calibration isert above) as a function of off-axis angle and energy and will be verified on orbit using

2/32 3/43 4/23	the sources listed below.				
5 Orbit6 Orbit7 Orbit8 Orbit9	Source	Count Rate (cps)	Mode	Exposure (ks)	Purpose
	PKS 0537-441	0.45	PC	5	First ligh co-alignn
	NGC 2516	0.002 - 0.01	PC	50	Accurate scale
Snapshot 3/45 4/25	PKS 0312-770	0.08	PC	80	PSF core
	RXJ0720.4-3125	0.16	PC	30	PSF core
Snapshot 3.4.5 	GX1+4	5.0	PC	20	PSF wing
	RXS J1708-4009	7.2	PC	20	PSF wing
	A. A.	10	1.2.5	120	

Effective Area The Effective Area of the XRT telescope has been measured at the Panter calibration facility as a function of off-axis angle and energy (left) and will be verified on orbit using the sources listed below. XRT Effective Area vs Energy Source Coun Mod Exposur (ks) Purpose Rate (cps) PC, WT Effective area, gain. Cas A 21 150 vignetting 2E0102-7212 4 PC, WT 126 Effective area, gain, vignetting Effective area, gain 790 PD 10 Crat vignetting

Energy Resolution

The in-flight performance of the instrument will be monitored daily using 5%Fe calibration sources illuminating the corners of the CCD. An image collected during thermal vacuum testing in July 2002 is shown below. The central circular region shows the circular field of view of the instrument (slightly truncated by the edges of the CCD), illuminated by Mn K-oand K-βX-rays at 5.9 and 6.4 keV (see spectrum below) from a ³⁵Fe source located on the camera door. During flight this source is moved away when the camera door is opened, and this portion of the CCD views the sky. The four circular regions in the corners of the detector are the in-flight calibration sources, which permit us to measure resolution, gain, and charge transfer efficiency (both scrial and narallel) as a function of time durine the mission.



Pictorial diagram of a typical "day in the life" of *Swift* observations covering 9 orbits. The middle box (yellow) shows a timeline for a sequence of snapshots of 5 different targets, four Pre-Planned Targets (PPTs) loaded into the on-board flight timeline, and one Automated Target (AT) representing a newly discovered GRB. Targets are color-coded for clarity. The top bar shows an expanded view of the first two orbits. Snapshots are identified by a target number and a snapshot number (target/snapshot). These PPTs would typically represent follow-up observations of GRBs discovered over the previous week. In Orbit 3 a new GRB is discovered by the BAT, and the Figure-of-Herrit (FOM) task (the on-board automatic scheduler) assigns it a target number of 5 and schedules an immediate observation, interrupting the previously-scheduled snapshot 34 for target #5. The automated observation of target #5 with snapshot #34. On Orbit 4, target #5 is observed as soon as it becomes visible, and preempts time from both target #1 and target #2 with snapshot #34. On Orbit 4, target #5 is observed as soon as not a performance and a PT (target #3). For the AT, the XRT budgets this has row and bias map during the sequence of XRT takes an image, centroids the image to determine the source position, and sends this to the ground through TDRSS. Along with a postage-stamp image of the source. It then switches back to Photodiode (PD) mode. As soon as the sequence of events for an APT (target #5). The sequence of events for an APT (target #5). The sequence of events for an APT (target #5). The sequence of events for an APT (target #5). The sequence of events for an APT (target #5). The sequence of the source. It then switches back to Photodiode (PD) mode. As soon as the seven (ATT image sequence) that no Image Mode data are collected and no TDRSS.

Swift Observation Scenario



Timeline of an XRT observation of an Automated Target (newly-discovered GRB). The new Snapshot begins when the observatory begins to slew to the new target. A typical slew will take between 20 and 50 s; here we show a slew time of 43 s followed by a worst-case settle time of 7 s. The XRT takes up to 5 s to determine the GRB centroid, and then begins the balance of an automated observation. As the flux decays (top line), the XRT modes switch accordingly. The Snapshot ends when a constraint violation triggers another slew. XRT mode and data products are shown in the center and bottom bars, respectively. TDRSS messages are shown in the bottom graphic. In this case, the Centroid Position message is generated at about 55 s and the Spectrum message is generated at about 400s.



F_<1 mCrabs

PC

XRT automated operations: this is a simplified flow-chart of an XRT observation of a new GRB. During the S/C slew we collect bias images and other calibration data. When the S/C arrives at the target we take a quick piled-up image, calculate the source centroid in RA and Dec, and sent the position to the GCN via TDRSS. We also send a 51x51 pixel "postage-stamp" image of the source to the GCN. We then switch into our possige samp image of the source of the Oct, we then switch into our fast timing mode (Photodiode Mode, or PD) until the flux drops below 600 mCrabs. We then switch into Windowed Timing (WT) mode and issue a raw spectrum through TDRSS to the GCN.

When the flux drops below 1 mCrabs we switch to Photon-Counting mode (PC; similar to the ACIS Timed Exposure mode) and issue another cumulative raw spectrum via TDRSS to the GCN





Additional calibration targets will measure timing accuracy and will provide cross-calibrations to RXTE, Chandra, and XMM. The total XRT calibration program uses about 1 Ms of observing time.